

6. PreREISE

This page is dedicated to the collection, processing and formatting of data that are fed to the simulation engine. PreREISE is an open source package written in Python that is available on [GitHub](#).

The generation of input data rely on the grid model. For this reason, you must have [PowerSimData](#) cloned in a folder adjacent to your clone of PreREISE.

Note:

Input data are publicly available for the Breakthrough Energy Sciences (BES) grid model (see [publication](#)). You don't need to generate any input data if you use the scenario framework to carry out power flow study.

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[6.1. General Comments](#)

Profiles are CSV (Comma Separated Values) files enclosing a series of data points indexed in time orders. The simulation engine expects a demand, hydro, solar and wind profile. All the profiles have UTC timestamp as indices. Columns are the zone IDs and plant IDs for the demand and hydro/solar/wind profiles, respectively. Values are load

in MWh in each zone for the demand and energy generated by a 1MW generator for hydro, solar and wind profiles.

The **[type]_v[D]** naming convention is used, where:

- **type** specifies the profile type (demand, hydro, solar or wind) and
- **D** refers to the date the file has been created using the 3 letters Month (e.g., Jan) and 4 digits Year (e.g., 2021) format.

If two or more profiles of the same type are created the same month of the same year, the different versions will be differentiated using a lowercase letter added right after the year, e.g, demand_vJan2021.csv (first), demand_vJan2021b.csv (second), demand_vJan2021c.csv (third) and so forth.

6.2. Demand

6.2.1. Historical

6.2.1.1. Texas

ERCOT publishes historical hourly load data for its eight weather zones. The data downloaded [here](#) are used as is to build the profile for the Texas Interconnection.

6.2.1.2. Western

Balancing authorities (BAs) submit their demand data to EIA and can be downloaded using an [API](#). The list of BAs in the Western Interconnection can be found on the website of the Western Electricity Coordinating Council (WECC) along with the area they approximately cover (see [map](#)).

Some data processing/cleaning is then carried out to derive the profile for the Western Interconnection:

- adjacent data are used to fill out missing values
- BAs are aggregated into the load zones of the grid model
- outliers are detected and fixed.

These steps are illustrated in the [western demand notebook](#).

6.2.1.3. Eastern

The construction of the Eastern Interconnection demand profile is slightly different from the Western counterpart. We still download historical demand data from EIA and perform the 3-step data processing/cleaning as for the Western Interconnection for all Balancing Authorities (BAs) but MISO (Midcontinent Independent System Operator) and SPP (Southwest Power Pool).

MISO and SPP operate across multiple U.S. states (e.g. 15 for MISO) and cover several load zones in our grid model. Instead of considering a single hourly profile shape for each entity and having load zones sharing the exact same profile in different part of the country, we further split MISO and SPP into subareas. The hourly subarea demand profiles for MISO and SPP can be downloaded on their respective website (check [SPP hourly load](#) and [MISO hourly load](#)). The geographical definitions of these subareas are obtained directly from contact at the BAs via either customer service or internal request management system (see the [RMS](#) for SPP). Given the geographical definitions, i.e., list of counties for each subarea, each bus within MISO and SPP is mapped to the subarea it belongs to.

The overall procedure is demonstrated in the [eastern demand notebook](#).

[6.2.2. Transportation Electrification](#)

[6.2.2.1. Summary](#)

The transportation sector is one of the five grand challenges of decarbonizing the economy. In order to accurately capture the future trend of transportation electrification and its interactions with the electricity sector and other sectors such as building and manufacturing, a high resolution and accurate transportation electrification model integrated into the simulation framework with other sectors is necessary. A few key questions arise when determining the additional load from electric vehicles on the electric grid – how many electric vehicles of which types are expected to be on the roads by a given year and what are the typical trip patterns, which in turn determines when charging is most likely to happen. As is frequently discussed, charging could have significant flexibility as to its precise timing, which ties this project into the Demand Flexibility project. In future highly integrated whole-economy energy systems, the optimal operation of the transportation sector is affected by other sectors, such as building sector. When electric vehicles are charged through chargers located in buildings, the distributed energy resources and space heating/cooling load in buildings could be optimized together with electric vehicle charging to achieve more emissions reduction and cost savings. This transportation model is one of the key components of the multi-sector integrated energy systems model.

The overall objective of the Transportation Electrification Project is to develop a module that can capture the additional electricity demand from most of the transportation sector, including electric LDVs, HDVs, and fleet vehicles (e.g., buses). The core activities include (1) development of detailed data sets that represent the electricity demand patterns due to vehicle mobility, growth in electric vehicle penetration, and flexibility parameters for electrified light-duty vehicles (LDVs) and heavy-duty vehicles (HDVs) consisting of private and publicly-owned fleets; (2) development of code that can generate electricity demand profiles for LDVs and HDVs under different levels of charging intelligence, and (3) integration of the modeling capability for determining electrified LDV and HDV load profiles into the open-access, large-scale grid model developed by the Breakthrough Energy Grid Modeling team.

6.2.2.2. Capabilities and Data

The transportation electrification module calculates an estimate of the additional hourly electricity demand from the electrification of transportation vehicles for all U.S. urban and rural areas for years ranging from 2017-2050. The hourly estimation builds upon data collected representing over half a million driving events.

Additional data sets allow for profiles to be generated across the following dimensions:

- 4 vehicle types (light-duty vehicles (LDV), light-duty trucks (LDT), medium-duty vehicles (MDV), and heavy-duty vehicles (HDV))
- 33 simulation years (2017-2050)
- 481 Urban Areas (as defined by the U.S. Census Bureau) and 50 Rural Areas (one for each U.S. State).

The charging of each vehicle is currently simulated via one of two methods: Immediate Charging and Smart Charging. Immediate Charging simulates charging occurring from the time the vehicle plugs in until either the battery is full or until the vehicle departs on the next trip. An example profile is in orange below, added on top of the base load demand ([Fig. 6.1](#)).

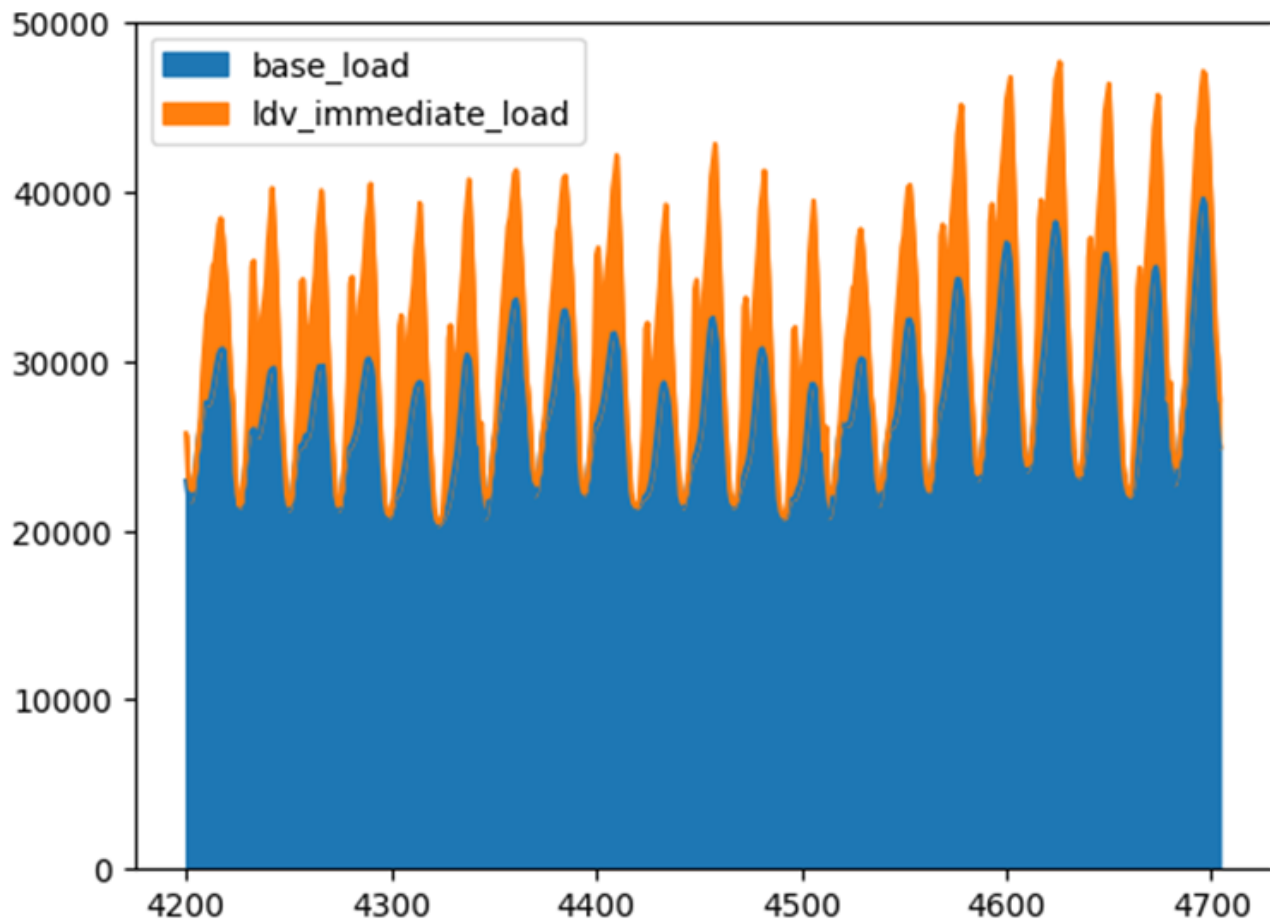


Fig. 6.1 Example of LDV Immediate Charging Stacked on Top of Base Load (3 Weeks)

Smart Charging refers to coordinated charging in response to a user-adjustable objective function. The example profile below ([Fig. 6.2](#)) provides the same amount of charging to the same set of vehicles in the Immediate Charging figure above ([Fig. 6.1](#)). This instance of Smart Charging manages the peak demand of the base load plus the additional transportation electrification load to be substantially lower ($\sim 50\text{GW}$ vs $\sim 40\text{GW}$ in this example case).

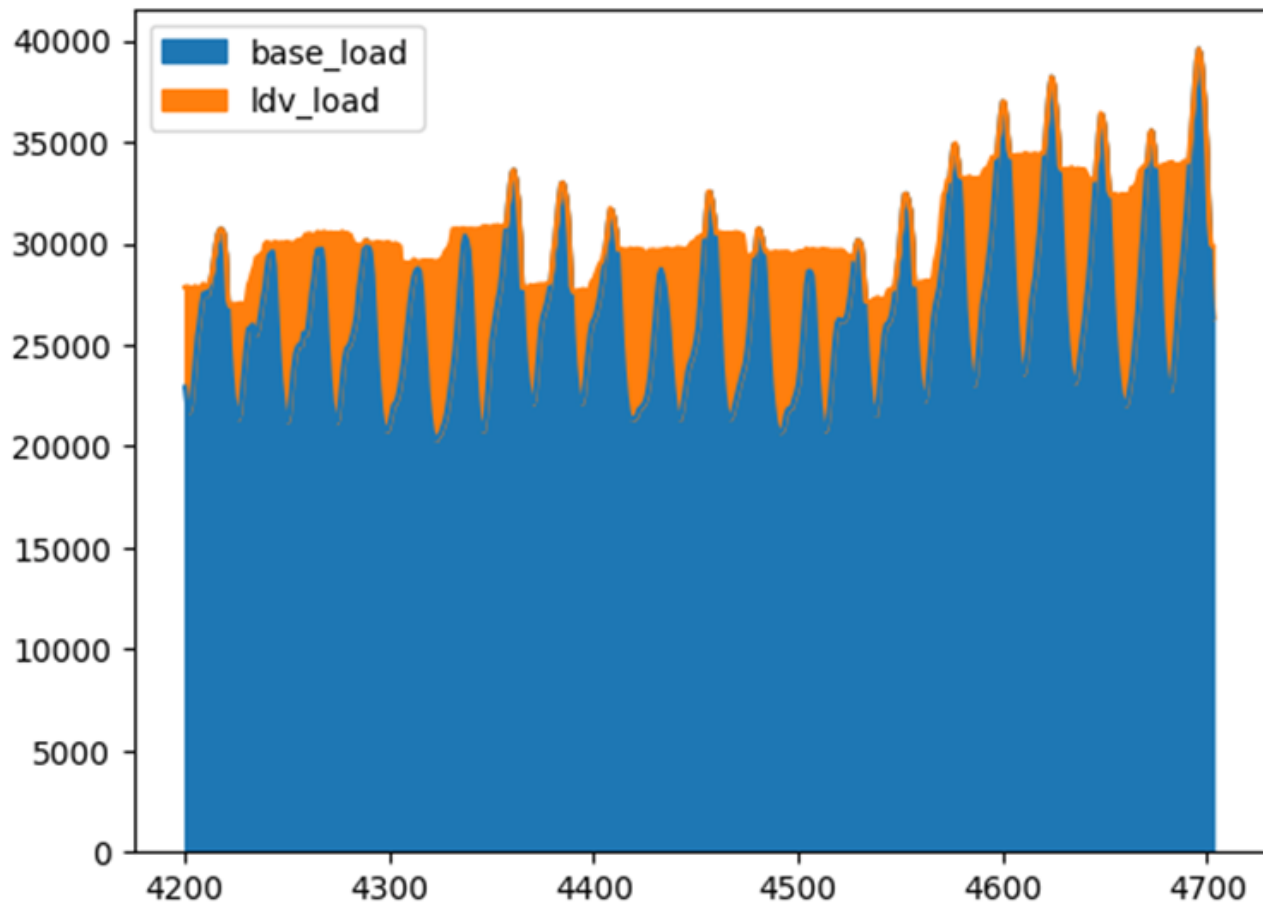


Fig. 6.2 Example of LDV Smart Charging “Filling in the Valleys” of Base Load (3 Weeks)

6.2.2.3. User Manual

6.2.2.3.1. Pre-processed input data

The following data is provided for the user or could be overridden via an input from the user with a different preferred data set.

- Annual projections of vehicle miles traveled (VMT) are calculated in advance and are provided for the user for all Urban Areas in the U.S. Each state also has a VMT projection for the Rural Area in that state. See Section 3.1 below for calculation process details using data from NREL’s Electrification Futures Study and the Department of Transportation’s Transportation and Health Indicators.
- Projections of the fuel efficiency of battery electric vehicles are provided from NREL’s Electrification Futures Study, with more detail in Section 3.4 below.
- Each vehicle type (light-duty vehicles (LDV), light-duty trucks (LDT), medium-duty

vehicles (MDV), and heavy-duty vehicles (HDV)) has a data set with vehicle trip patterns that is used by the algorithm to represent a typical day of driving. See Sections 1 and 2 for more details on the input data from the National Household Travel Survey (NHTS) and the Texas Commercial Vehicle Survey.

- Each typical day of driving is scaled by data from EPA’s MOVES that captures the variation in typical driving behavior across (i) urban/rural areas, (ii) weekend/weekday patterns, and (iii) monthly driving behavior (e.g. more driving in the summer than the winter).

6.2.2.3.2. Calling the main Transportation Electrification method

With the above input data, the main function call for the transportation module is `generate_BEV_vehicle_profiles` and is called using a few user-specified inputs:

1. Charging Strategy (e.g. Immediate charging or Smart charging)
2. Vehicle type (LDV, LDT, MDV, HDV)
3. Vehicle range (whether 100, 200, or 300 miles on a single charge)
4. Model Year
5. Urban Area / Rural Area that is being modelled

Depending on the spatial region included in the broader simulation, the user can run a script across multiple Urban Areas and Rural Areas to calculate the projected electricity demand from electrified transportation for the full spatial region. From there, a spatial translation mechanism (described next) converts this demand to the accompanying demand nodes in the base simulation grid.

6.2.2.3.3. Spatial translation mechanism – between any two different spatial resolutions

We have developed a module called `prereise.utility.translate_zones`. It takes in the shape files of the two spatial resolutions that the user would like to transform into one from the other. Then a transformation matrix that gives the fractions of every region in one resolution onto each region in the other resolution will be generated based on the overlay of two shape files. Finally, the user can simply multiply profiles in its original resolution, such as Urban/Rural Areas, by the transformation matrix to obtain profiles in the resultant resolution, such as load zones in the base simulation grid. This allows each module to be built in whatever spatial resolution is best for that module and to then transform each module into a common spatial resolution that is then used by the multi-sector integrated energy systems model.

6.2.2.4. Methodology

6.2.2.4.1. EV Charging Model Process and Flowchart

This EV charging model simulates the charging behavior of the following on-road vehicle categories: light-duty vehicles (LDV), light-duty trucks (LDT), medium-duty vehicles (MDV), and heavy-duty vehicles (HDV). The default LDV and LDT trip data come from the 2017 National Household Travel Survey (NHTS), with an example of the data included in [Fig. 6.3](#).

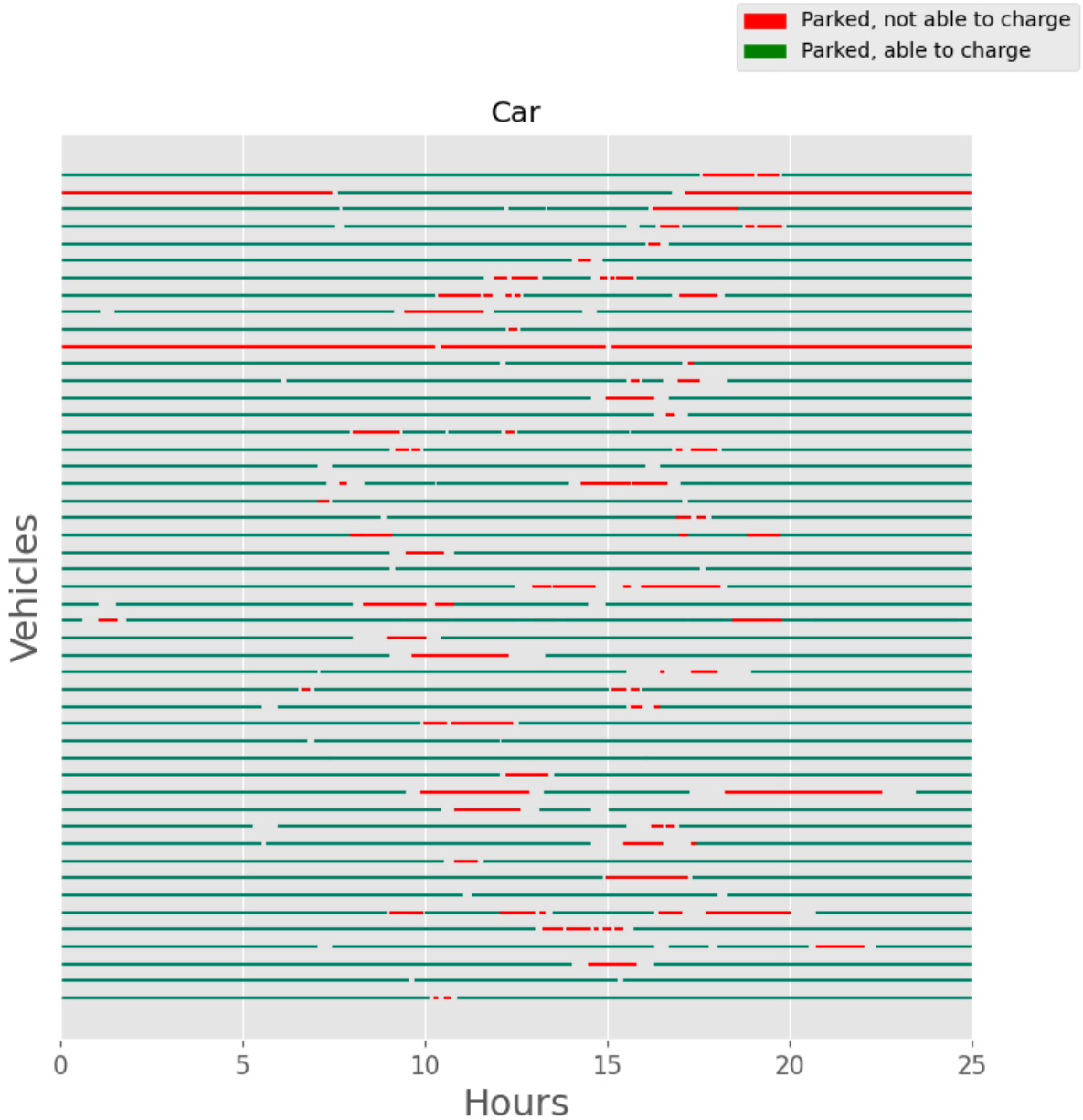


Fig. 6.3 Example Daily Trips of Vehicle data from NHTS

These are also divided into Census Divisions, which are then mapped to the correspond-

ing regions within the grid model. The MDV and HDV trip data are anonymized from the Texas Commercial Vehicle Survey and calibrated to align with medium- and heavy-duty vehicle trip statistics. More details about each data set are included in [Section 6.2.2.4.2](#) and can be updated to reflect different vehicle scenarios or incorporate more recent data. In all cases, an average weekday and average weekend daily pattern of vehicle trips is calculated from the vehicle trip data. Then, these trips are filtered by vehicle type (e.g. LDV, LDT, MDV, and HDV) and by range for LDVs and LDTs (e.g. less than 100 miles, less than 200 miles, less than 300 miles) to capture what is capable for typical battery capacities. This creates a weekday and weekend daily pattern of BEV-capable trips that will be used in the subsequent steps. The LDV and LDT vehicle miles traveled (VMT) by hour is presented in [Fig. 6.4](#).

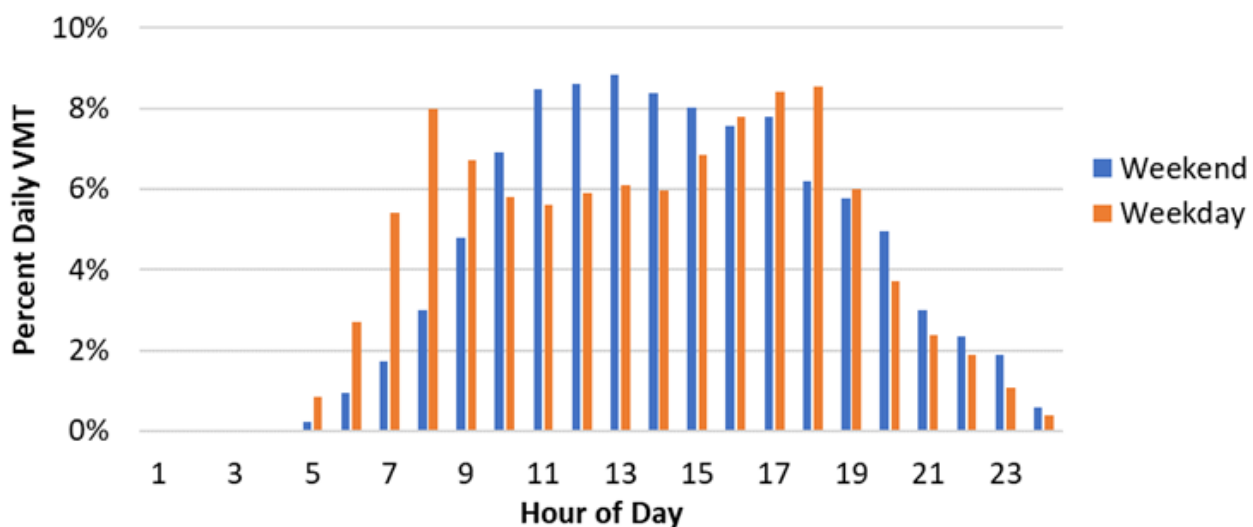


Fig. 6.4 Light-Duty Vehicle/Truck Miles Traveled by Hour of the Day for Weekends and Weekdays

Similarly, [Figure Fig. 6.5](#) illustrates the percentage of vehicles parked and able to charge at each hour over a 24-hour period.

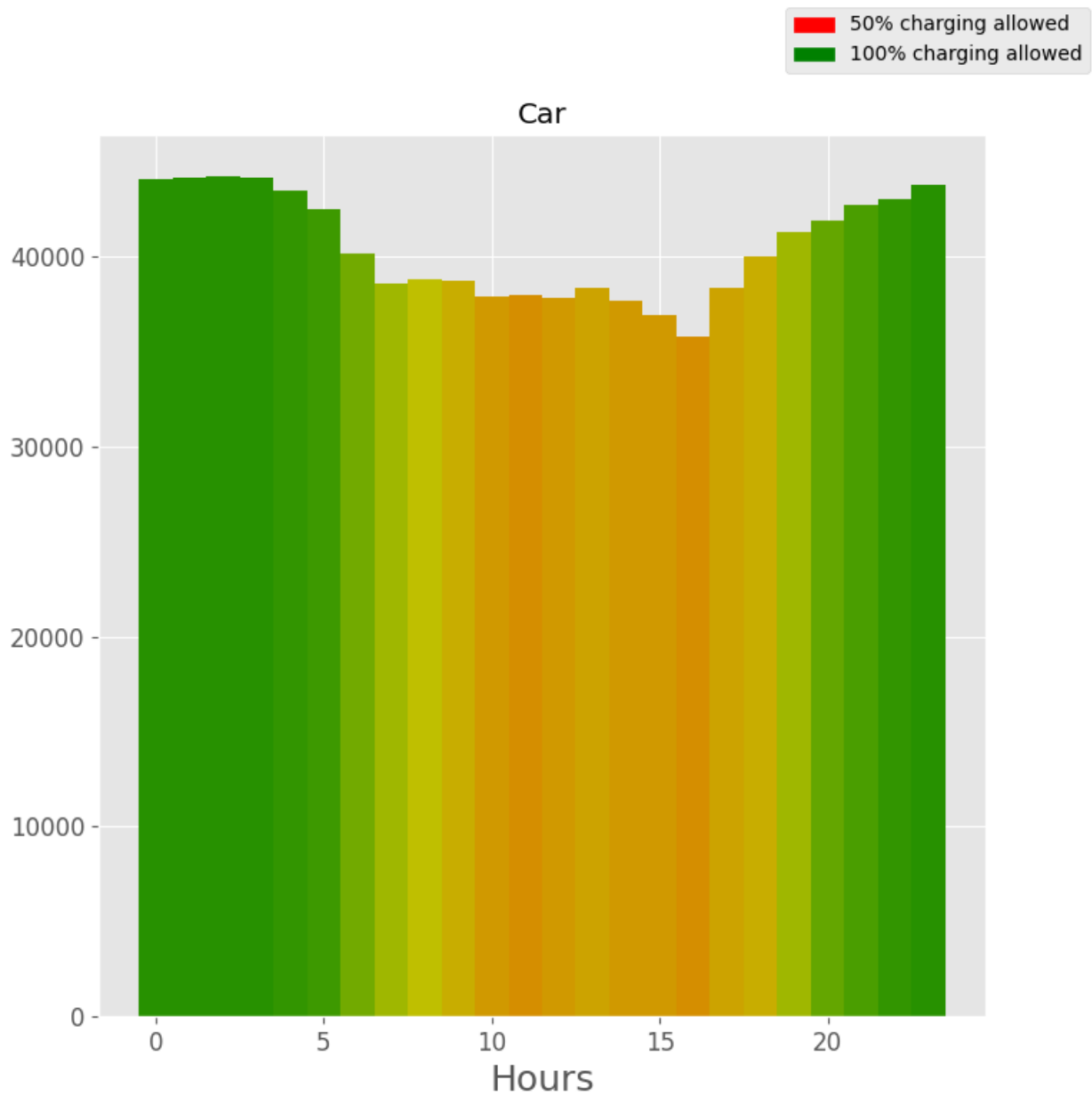


Fig. 6.5 Status of Dwelling Vehicles over 24-hour Period

The flowchart in [Fig. 6.6](#) illustrates the entire procedure.

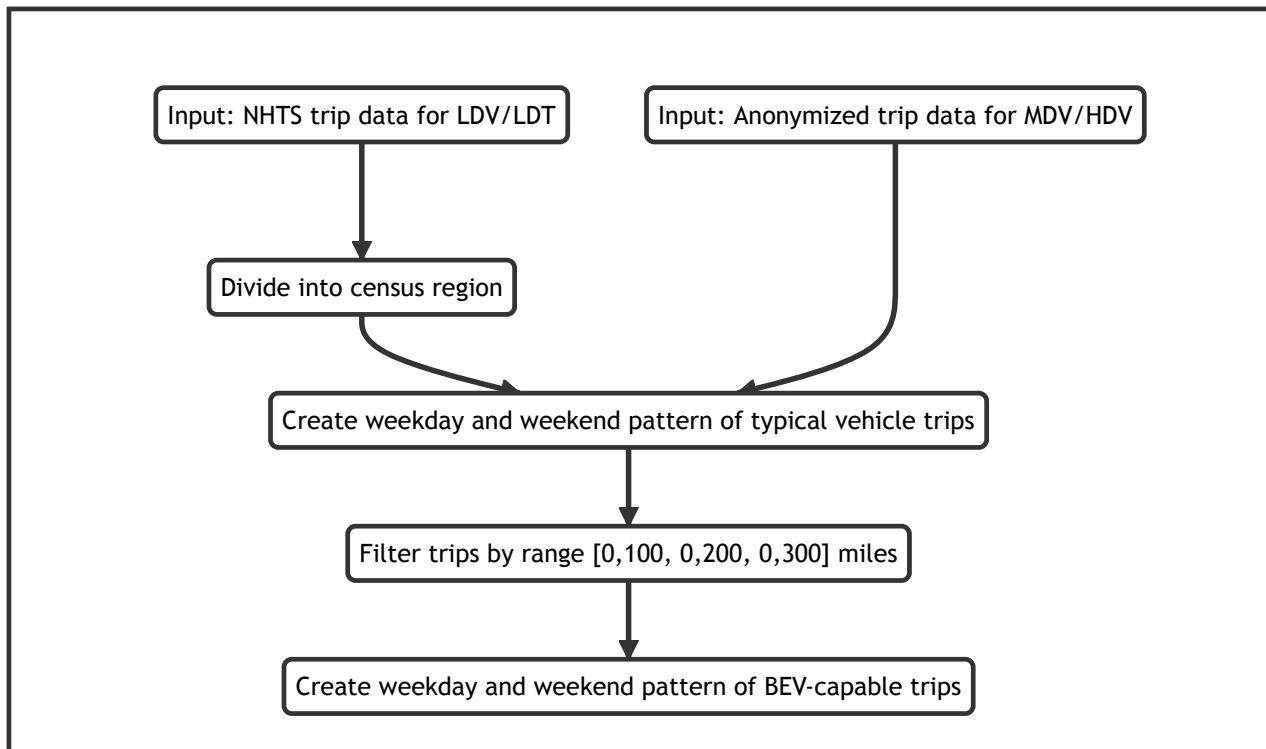


Fig. 6.6 Daily BEV-Capable Trip Patterns

These daily BEV-capable trip patterns are then further distributed temporally and spatially, as discussed in more detail in [Section 6.2.2.4.3](#). State-level and urban area (UA) VMT per capita were taken from the Department of Transportation’s transportation health tool and create the distribution across rural and urban areas, as defined by the U.S. Census Bureau [\[1\]](#), [\[2\]](#). Weight factors from the U.S. EPA model, MOVES, create the time-of-year scaling of weekday versus weekend and month of the year [\[3\]](#).

Projections from NREL’s Electrification Futures Study (EFS) provide the adoption rate scaling of BEV demand to create the base-year and simulation-year profiles of BEV-capable trip patterns [\[4\]](#). Total charging demand by area (urban and rural) is scaled based on state-level BEV VMT projections from NREL’s EFS [\[5\]](#). As more granular BEV projections become available, scaling projections could be targeted to specific urban and rural areas given the model’s structure. The procedure is shown in [Fig. 6.7](#).

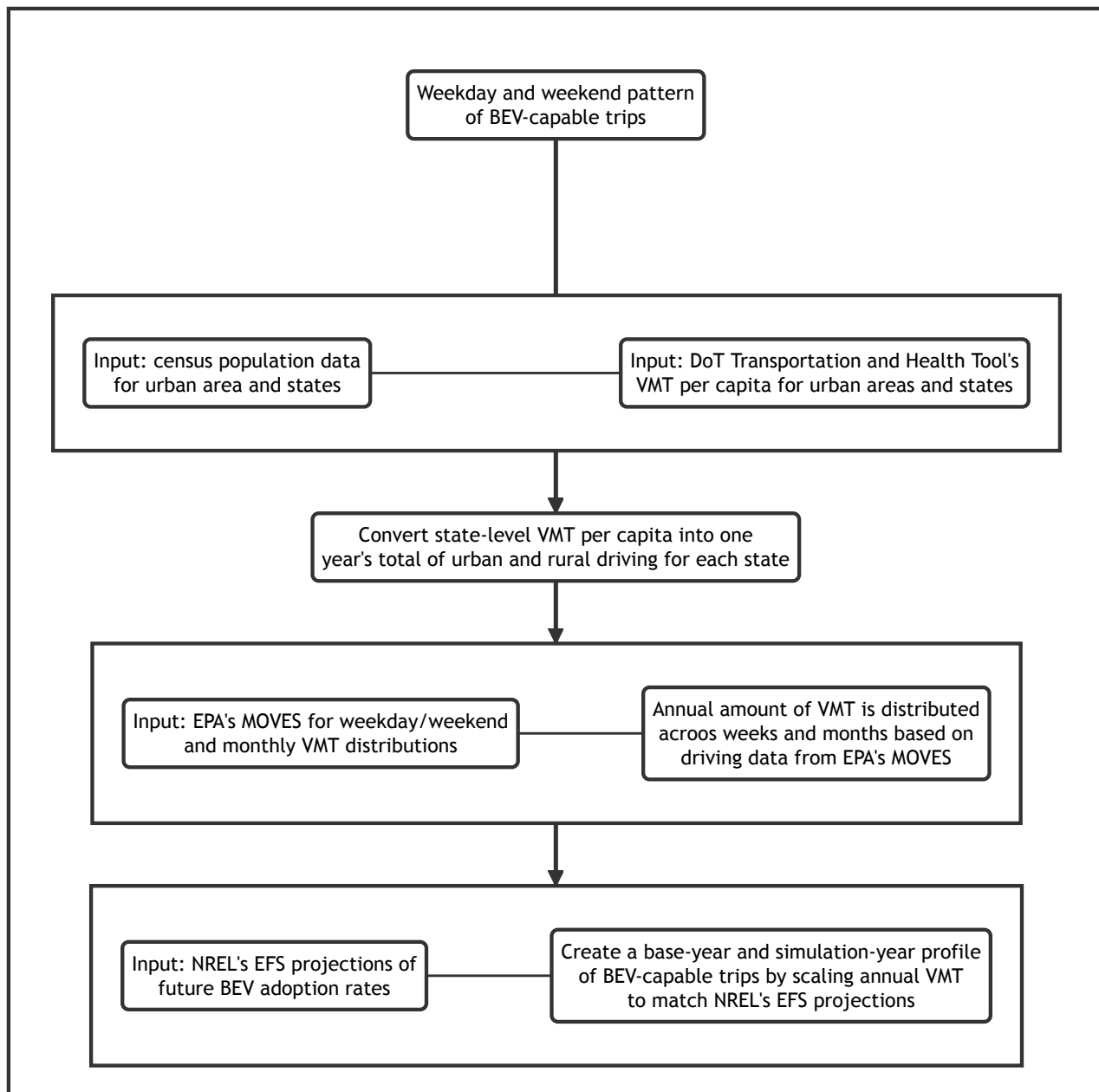


Fig. 6.7 Simulating base-year and simulation-year dynamics

Algorithmically, these projections are modeled by making multiple copies of individual trips, as illustrated in [Fig. 6.8](#), which are used in the smart charging algorithm.



Fig. 6.8 Scaling process of vehicle trip

With the projected BEV vehicle trips in place, NREL's EFS is again used to set the fuel efficiency for the simulated year to determine the amount of electricity needed to charge after each BEV trip. Then, the charging model uses one of two charging algorithm strategies: immediate (uncoordinated) charging and smart (optimal) charging, with example illustrations shown in [Fig. 6.10](#) and [Fig. 6.11](#). Both algorithms are deterministic and directly utilize the input vehicle trip data to calculate the charging demand based on vehicle travel distances, dwell locations, and user defined infrastructure parameters. The Smart Charging algorithm currently uses an optimization function to minimize wholesale prices via flattening the net load curve. Incorporating additional optimization goals that will change the cost function, such as minimizing individual vehicle costs in response to time-varying utility rate structures, will be explored in future work. For the Smart Charging algorithm, each representative vehicle sequentially sets its charging pattern in response to the optimization function as well as an aggregate load profile. That vehicle's additional charging load is then added to the aggregate load profile, which is then sent to the next vehicle as an input to its smart charging decision. The aggregate profile of electricity demand from all smart-charging BEVs is then simply the sum across all vehicles (see [Fig. 6.9](#)).

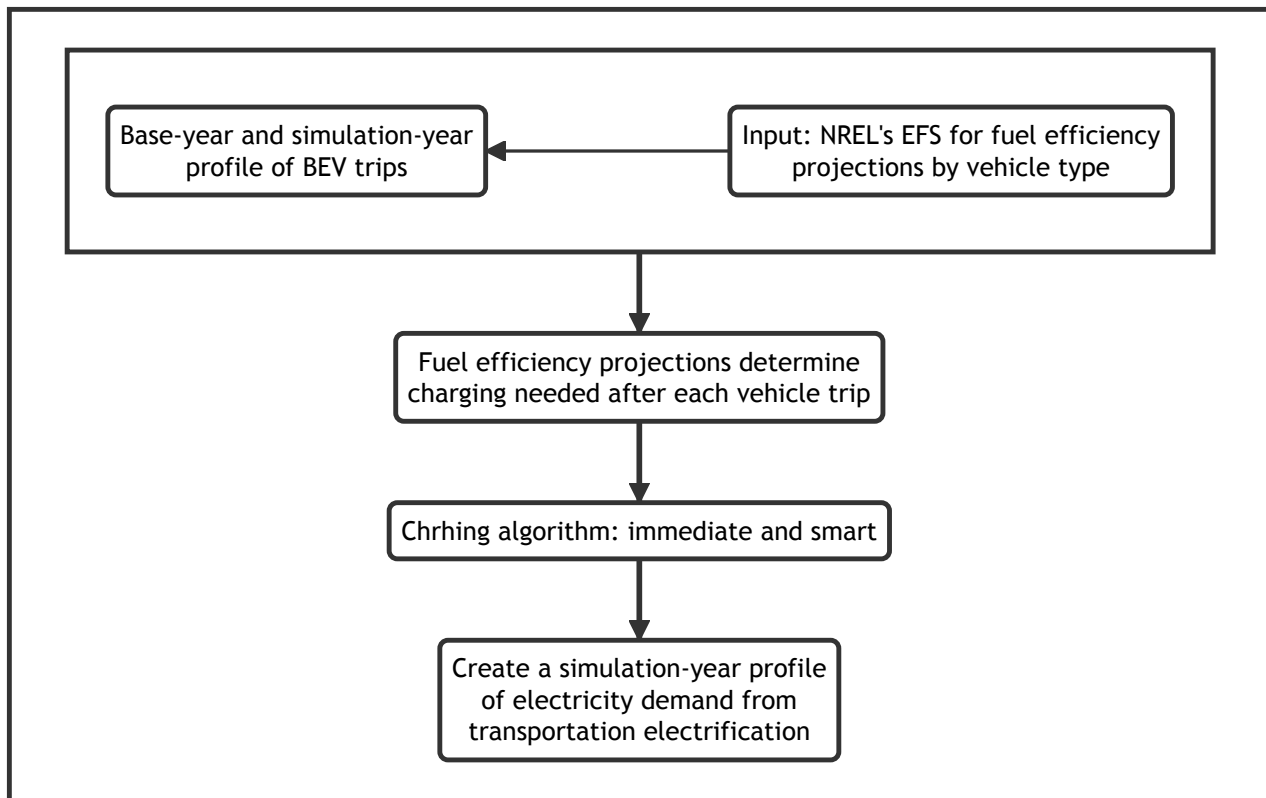


Fig. 6.9 Calculating simulation-year electricity demand

6.2.2.4.1.1. Immediate and Smart Charging Example Outputs

Immediate Charging refers to full power charging at time of plug-in until full capacity reached or car unplugged, whichever comes first.

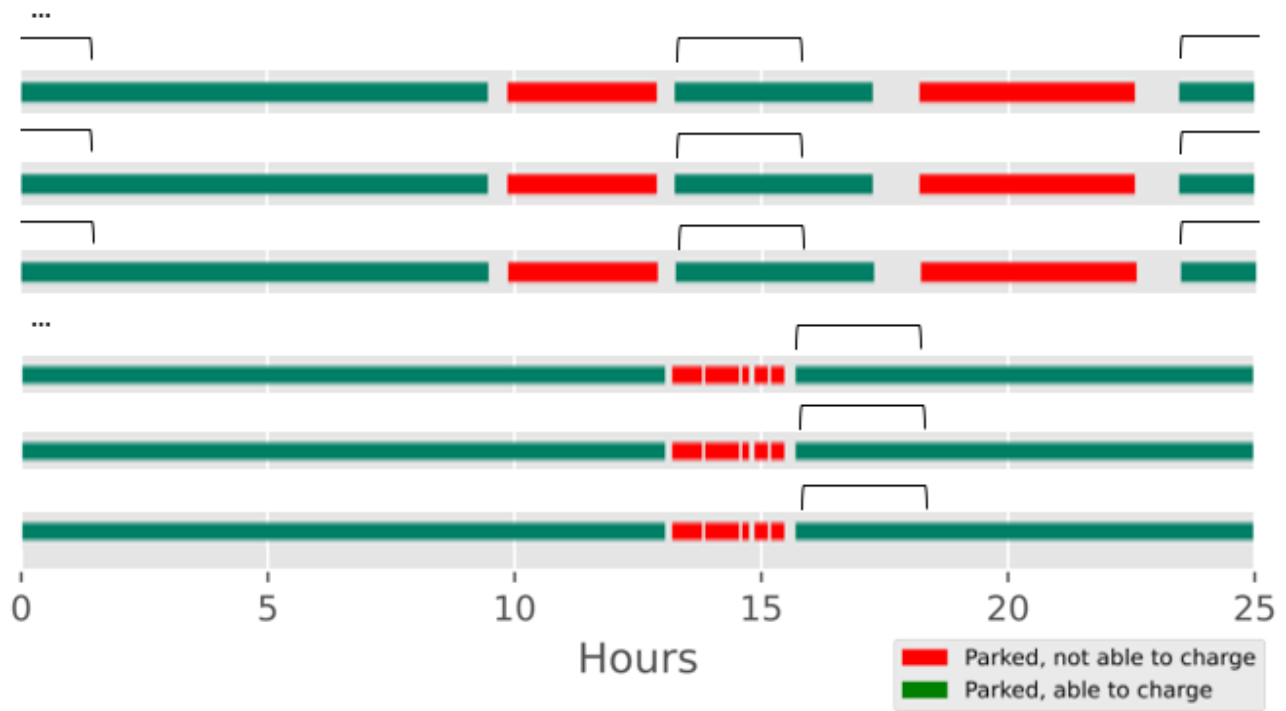


Fig. 6.10 Notional results for immediate charging algorithm, with charging hours within the bracket

Smart charging refers to coordinated charging, where drivers provide information on their travel schedule and charging demand to the electric grid operator.

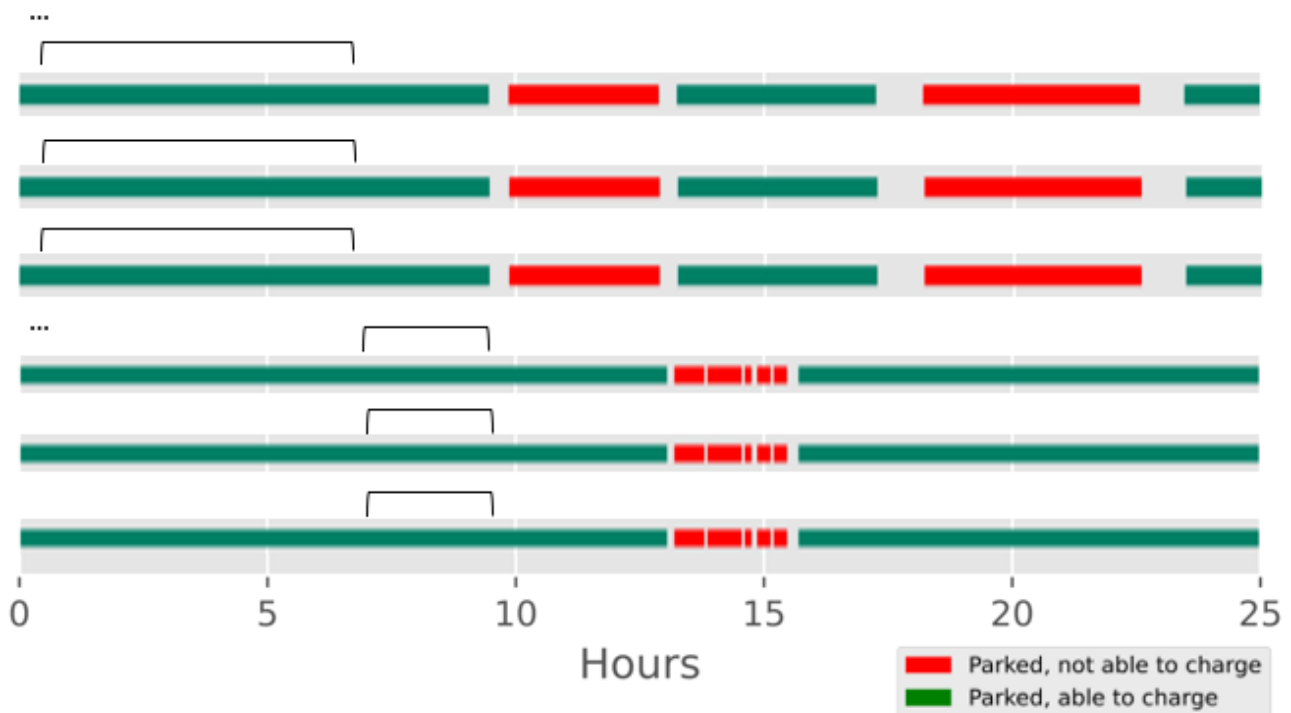


Fig. 6.11 Notional results for smart charging algorithm, with charging hours within the bracket

Example Output – Immediate Charging. Immediate Charging refers to full power charging at time of plug-in until the battery is full or until the vehicle departs on the next driving trip. [Fig. 6.12](#) and [Fig. 6.13](#) present normalized, unscaled LDV and LDT charging demand, respectively. These normalized profiles are then scaled based on the parameters for the desired simulation year, with an example output shown in [Fig. 6.1](#). These include the projected VMT for the simulated year, the fuel efficiency projection (e.g. number of kWh used per mile traveled), and the efficiency of the charging process.

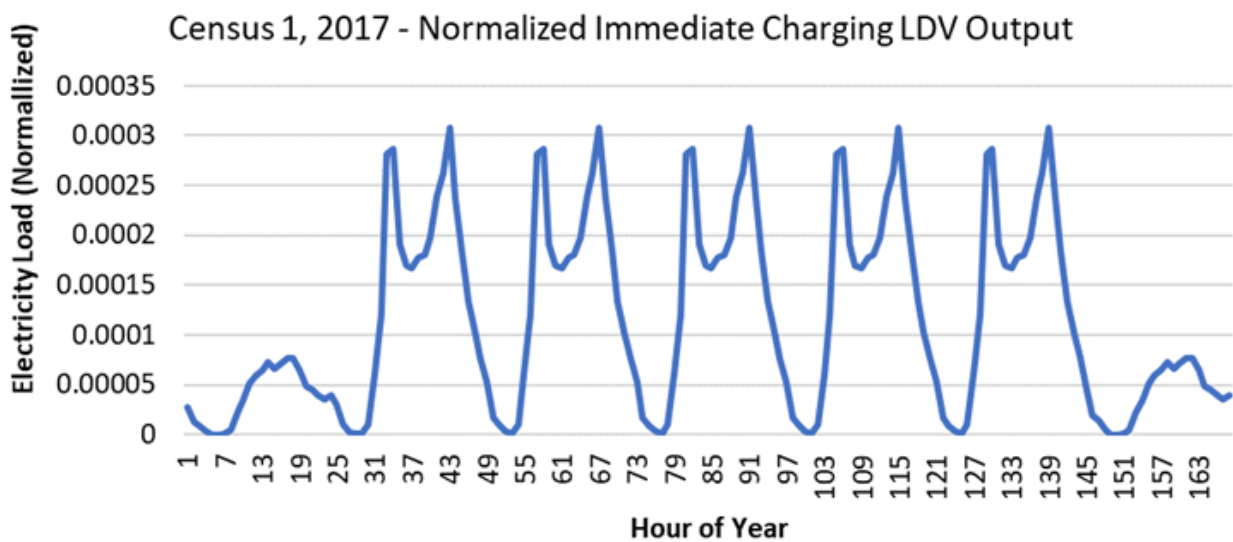


Fig. 6.12 Normalized LDV immediate charging output for 168 hours (1 week)

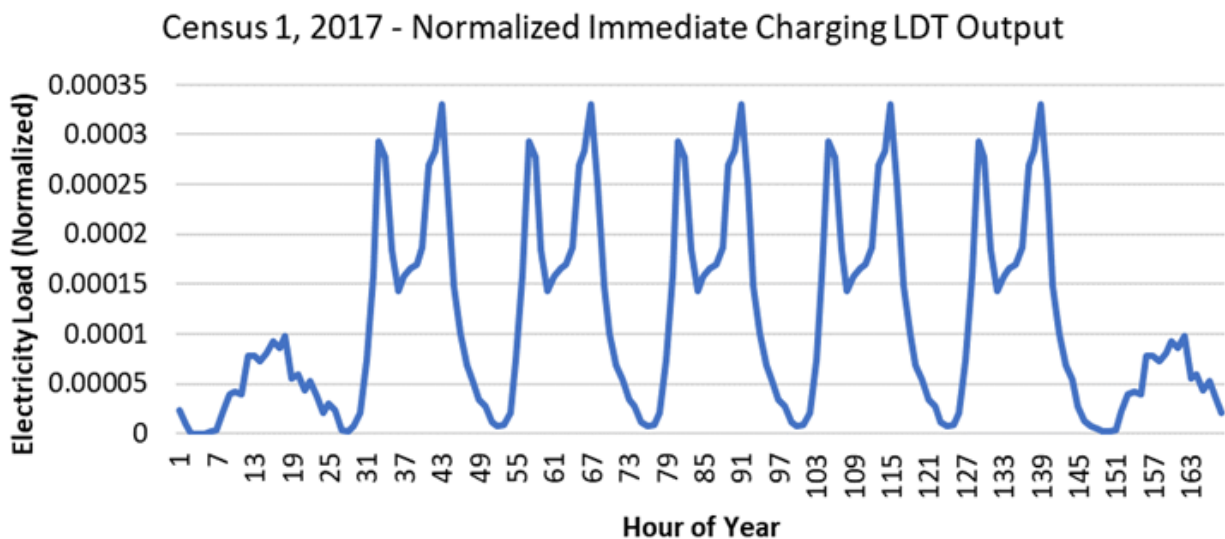


Fig. 6.13 Normalized LDT immediate charging output for 168 hours (1 week)

Example Output – Smart Charging. Smart charging refers to coordinated charging, where drivers provide information on their travel schedule and charging demand to the electric grid operator. Vehicle charging is optimized based on cost (e.g., time-of-use rates), grid support needs, travel considerations, and vehicle constraints. Fig. 6.14 and Fig. 6.15 present normalized, unscaled LDV and LDT smart charging demand, respectively. Fig. 6.2 shows an example of the results from LDV smart charging at scale that was optimized for grid support needs by flattening net demand (e.g. “filling in the valleys”).

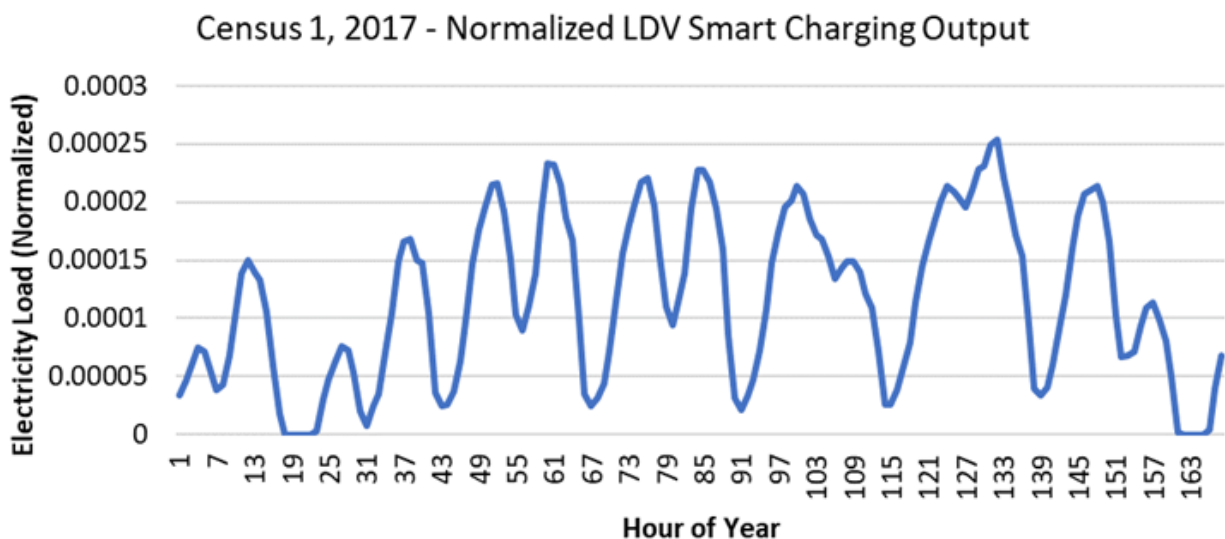


Fig. 6.14 Normalized LDV smart charging output for 168 hours (1 week)

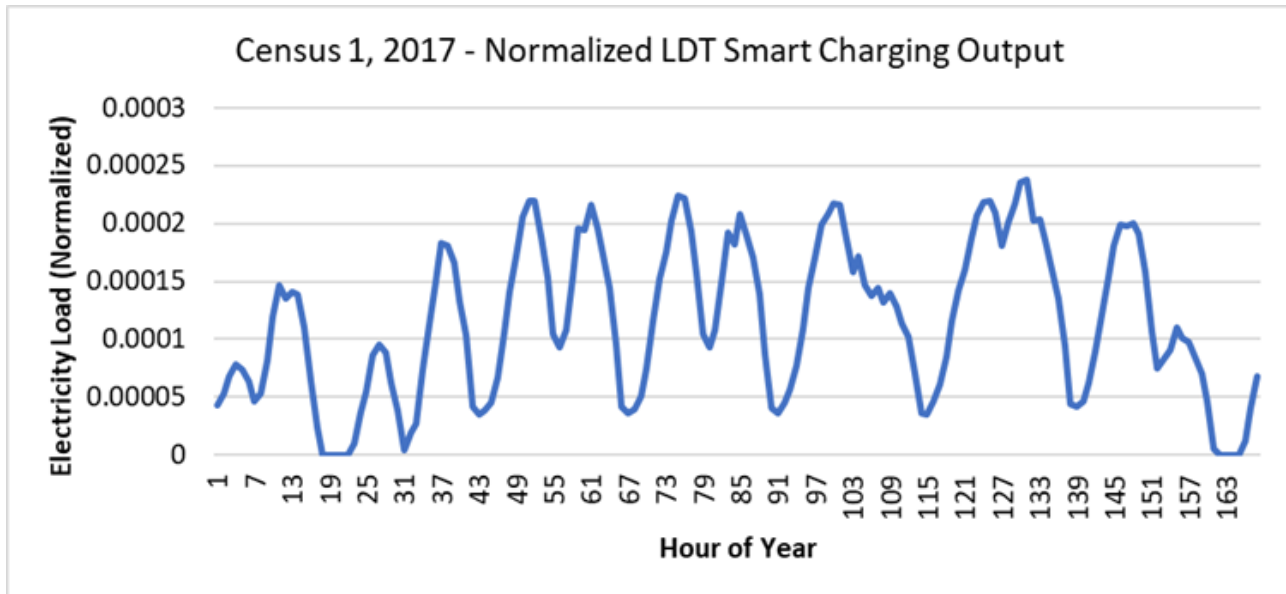


Fig. 6.15 Normalized LDT smart charging output for 168 hours (1 week)

6.2.2.4.2. Vehicle Travel Patterns

6.2.2.4.2.1. Light-duty Travel patterns

The 2017 National Household Travel Survey (NHTS) documents the light-duty vehicle and light-duty truck travel patterns (<https://nhts.ornl.gov/>). Data from the NHTS 2017 `trippub.csv` dataset were filtered to identify all vehicle trips. Relevant data were then divided into nine datasets, one for each Census Division, as defined within the dataset, see [Table 6.1](#).

Table 6.1 Census divisions

Division Number	Name	States Included
01	New England	CT, MA, ME, NH, RI, VT
02	Middle Atlantic	PA, NJ, NY
03	East North Central	IL, IN, MI, OH, WI
04	West North Central	IA, KS, MN, MO, ND, NE, SD

Division Number	Name	States Included
05	South Atlantic	DE, FL, GA, MD, NC, SC, VA, WV, (DC)
06	East South Central	AL, KY, MS, TN
07	West South Central	AR, LA, OK, TX
08	Mountain	AZ, CO, ID, MT, NM, NV, UT, WY
09	Pacific	AK, CA, HI, OR, WA

The definition for each column in the final datasets is in [Table 6.2](#). Columns 1-20 are taken directly from the NHTS dataset, and columns 21-28 are calculated values based on the preceding columns.

Table 6.2 Columns in Modified NHTS Trip Dataset

Column	Variable
1	Household
2	Vehicle ID
3	Person ID
4	Scaling Factor Applied
5	Trip Number
6	Date (YYYYMM)
7	Day of Week (1 - 7)
8	If Weekend
9	Trip Start Time (HHMM)
10	Trip End Time (HHMM)
11	Travel Minutes
12	Dwell Time
13	Miles Traveled
14	Vehicle Miles Traveled
15	Why From

Column	Variable
16	Why To
17	Vehicle Type (1-4 LDV, 5+ LDT)
18	Household Vehicle Count
19	Household Size
20	Trip Type
21	Start Time (hour decimal)
22	End Time (hour decimal)
23	Dwell Time (hour decimal)
24	Travel Time (hour decimal)
25	Vehicle Speed (mi/hour)
26	Sample Vehicle Number
27	Total Vehicle Trips
28	Total Vehicle Miles Traveled

Total vehicle trips variable refers to the total number of trips a single vehicle takes in the sample window (24 hours). Trips are divided into weekday and weekend trips. The resulting charging profile for each day type is replicated across the year, i.e., each weekday and each weekend are the same set of trips across the year. [Table 6.3](#) presents the total number of trips in the trip datasets for each vehicle category. The weekday and weekend trips are weighted based on the MOVES weight factors. The charging demand is scaled up and down further based on the MOVES monthly weight factors depending on the month of the year.

Table 6.3 Trip count by vehicle category, census division, and day of week

Vehicle Category	Census Division	Trip Count	
		Weekday	Weekend
LDV	01	3979	1235
	02	32831	10664
	03	30815	5116
	04	8962	2885
	05	58173	9620

Vehicle Category	Census Division	Trip Count	
		Weekday	Weekend
	06	2294	611
	07	52982	7818
	08	9127	2033
	09	53554	16386
LDT	01	2881	935
	02	29513	9347
	03	31788	5478
	04	10157	2960
	05	58900	9465
	06	2416	678
	07	60929	8530
	08	10006	2084
	09	40161	12116
MDV	All	8302	same
HDV	All	8407	same

6.2.2.4.2.2. Medium- and Heavy-duty Vehicles

The construction of the original representative datasets is described in [6].

The following is a description of the data that are rendered from the initial, representative HDV dataset.

1. Trip times, trip count, and miles traveled – data on trips was taken from the original trip datasets and scaled to align with known statistics for the target region. Only trip count, times, and miles traveled were included. Information on locations, vehicle identity, vehicle class, and vocation are excluded.
2. Dwell location – dwell locations are simplified to being either a “home base location” or not. Home base locations are defined as depots that are owned, managed, and/or under contract with the same entity as the fleet vehicle.
3. Trip start and stop times – travel and dwell times by time of day.

The final data table structure is presented in [Table 6.4](#). Each row of the data table is a unique trip taken by the specified vehicle.

Table 6.4 Columns in modified MDV and HDV trip datasets

Column	Variable	Description
1	Vehicle Number	Unique vehicle number
2	Trip Number	Current trip number of vehicle
3	Destination (home base or not)	Where the trip ends, 1 = home base, 2 = not home base
4	Trip Distance	Miles traveled in the trip
5	Trip Start	Time of trip start
6	Trip End	Time of trip end
7	Dwell Time	Length of time vehicle parked between trips
8	Trip Time	Length of travel time
9	Total Vehicle Trips	Total count of trips taken by the identified vehicle in the time window
10	Total Vehicle Miles	Total vehicle miles traveled by vehicle in time window

[6.2.2.4.3. Annual Vehicle Miles Traveled](#)

The model is structured for a single base year and three future years: 2017, 2030, 2040, and 2050. Each year is unique based on vehicle miles traveled (VMT) and fuel economy (miles per gallon of gasoline equivalent, mi/GGE), which together determine annual vehicle electricity demand. The base year and future projections of battery electric vehicle miles traveled are taken from NREL's Electrification Futures Study [4]. BEV VMT is divided into VMT occurring in Urban Areas (UA) and Rural Areas (RA). UA is a term assigned by the U.S. Census Bureau and is described as areas with a population of 50,000 people or more [2]. Other years are available from NREL, if desired.

[6.2.2.4.3.1. Electric Vehicle Miles Traveled Projections by Urban and Rural Area](#)

VMT per capita for each state and Urban Area (UA) was taken from the Department of Transportation's transportation health tool [1]. To determine total state VMT, state population was taken from Census data and was multiplied by the above state VMT per capita data [1] [2]. Then, to calculate the fraction of total state VMT that is allocated to

each urban area (UA) and rural area (RA), the UA population was also pulled from Census data [2]. From there, the UA population was multiplied by UA VMT per capita to get total UA VMT. Lastly, UA VMT is subtracted from state VMT to determine the RA VMT for the state. These calculations are summarized below:

$$V_{state} = A_{state} \times P_{state}$$

where:

V_{state} is the state VMT,
 A_{state} is the VMT per capita,
 P_{state} is the state population.

$$V_{UA} = A_{state} \times P_{UA}$$

where:

V_{UA} is the urban area VMT,
 P_{UA} is the urban area population.

$$V_{RA} = A_{state} - \sum V_{UA}$$

where:

V_{RA} is the rural area VMT.

6.2.2.4.3.2. Monthly and Daily Weight Factors

Along with the rural/urban distribution, the default scenarios also use weekday/week-end and monthly weight factors to distribute annual VMT. These weight factors come directly from the U.S. Environmental Protection Agency’s MOfor Vehicle Emission Simulator (MOVES) model [3]. The weight factor values are listed in [Table 6.5](#) and [Table 6.6](#).

Table 6.5 Weekday versus weekend weight factors

Day Type	Rural	Urban
Weekday (divided over 5 days)	0.72118	0.762365
Weekend (divided over 2 days)	0.27882	0.237635

Table 6.6 Month weight factors

Month	Weight Factor
January	0.0731
February	0.0697
March	0.0817

Month	Weight Factor
April	0.0823
May	0.0875
June	0.0883
July	0.0923
August	0.0934
September	0.0847
October	0.0865
November	0.0802
December	0.0802

6.2.2.4.3.3. BEV VMT Projections

To calculate the BEV VMT by vehicle class for each UA, state-level BEV VMT projections were based on the NREL Electrification Futures Study for 9 vehicle types [4]:

1. LDV BEV Cars: 100 mi, 200 mi, 300 mi
2. LDV BEV Trucks: 100 mi, 200 mi, 300 mi
3. BEV Transit Buses
4. MDV Trucks
5. HDV Trucks

Projections were used for 2030, 2040, and 2050. The 2017 base year assumptions were calibrated based on historical data. For all years, BEV VMT at the state level was translated to BEV VMT at the UA level by multiplying the state-level projections by the fraction of state VMT allocated to each UA. It is assumed that the proportion of VMT occurring in urban areas relative to total state VMT will be constant moving into the future. There are some UAs that did not have VMT data. Out of 481 UAs, 56 did not have VMT per capita data from the DOT, so those entries are zeros.

Once each UA and the state's RA have their projected annual VMT for a simulation year, the annual VMT is distributed to each day of the year based on weight factors from U.S. EPA MOVES model, see [Table 6.7](#). Each daily weight factor represents the fraction of annual VMT that is traveled in that specific day. The daily weight factors vary by month, whether the VMT is in a UA or a RA, and whether the day is a weekday or a weekend day. For example, within a given urban area all weekdays in January have the same weight factor and therefore the same allocated VMT.

Table 6.7 Urban and rural scaling factors by month and weekday vs weekend

	Urban		Rural	
Month	Weekday	Weekend	Weekday	Weekend
January	0.00252	0.00196	0.00238	0.00230
February	0.00266	0.00207	0.00251	0.00243
March	0.00279	0.00218	0.00266	0.00257
April	0.00296	0.00231	0.00268	0.00277
May	0.00299	0.00233	0.00285	0.00275
June	0.00313	0.00244	0.00297	0.00287
July	0.00321	0.00250	0.00301	0.00291
August	0.00319	0.00249	0.00304	0.00294
September	0.00302	0.00236	0.00285	0.00276
October	0.00298	0.00232	0.00282	0.00272
November	0.00284	0.00221	0.00270	0.00261
December	0.00279	0.00217	0.00262	0.00253

The trip data are scaled based on the allocated daily VMT. The daily patterns are adjusted by scaling the VMT of each trip within the daily patterns so that the total across the simulation matches the Annual VMT projection for each state.

6.2.2.4.3.4. Fuel Efficiency Projections

NREL’s Electrification Futures Study also projects average BEV fuel economy over time, based on assumptions regarding technology improvements and vehicle range [5]. NREL provides a range of possible BEV fuel economies (“Slow Advancement”, “Moderate Advancement”, and “Rapid Advancement”). The charging model uses mid-range values as the default fuel economy for each vehicle category and year, as shown in [Table 6.8](#).

Table 6.8 Default BEV fuel economy by vehicle category and year

Vehicle Type	Fuel Economy (mile/GGE)			
	2017	2030	2040	2050
LDV BEV cars, 100 mile range	138	156	158	160
LDV BEV cars, 200 mile range	129	152	155	156

Vehicle Type	Fuel Economy (mile/GGE)			
	2017	2030	2040	2050
LDV BEV cars, 300 mile range	122	148	152	154
LDT BEV trucks, 100 mile range	103	105	106	107
LDT BEV trucks, 200 mile range	97	103	104	104
LDT BEV trucks, 300 mile range	94	100	101	102
Transit buses	13	16	18	19
MDV trucks	16	21	23	24
HDV trucks	12	16	17	18

6.2.2.4.4. Smart Charging Optimization Algorithm

The smart charging algorithm was developed by [7]. The algorithm is a least cost optimization problem, with the cost function as follows:

$$\min \sum_{i=1}^n \sum_{j=1}^{seg(i)} f_{ij} x_{ij}$$

where:

f is the cost of electricity in [\$/kWh],

x is the increase in vehicle state of charge in [kWh],

i is the dwell period per trip count,

$seg(i)$ is the number of dwell segments for dwell period i ,

j is the dwell segment in [h],

n is the total number of dwell per trip periods

The total number of dwell segments $seg(i)$ will depend on the how long the vehicle is parked.

Equality constraint:

$$\sum_{i=1}^n \sum_{j=1}^{seg(i)} x_{ij} + \sum_{i=1}^n y_i$$

where:

y is the discharged energy from driving

Inequality constraints:

$$\begin{aligned}
y_1 &> -c \\
y_1 + \sum_{j=1}^{seg(1)} x_{1j} + y_2 &> -c \\
y_1 + \sum_{j=1}^{seg(1)} x_{1j} + y_2 + \dots + \sum_{j=1}^{seg(n-1)} x_{n-1j} + y_n &> -c
\end{aligned}$$

where:

c is the battery energy capacity in [kWh]

Bounds:

$$0 \leq x_{ij} \leq p_{ij} \times \Delta t_{ij} \times \eta$$

where:

p is the rated power of charger in [kW]

Δt is the dwell time in [h]

η is the charging efficiency

The optimization is structured to minimize the cost to charge each battery electric vehicle within defined battery constraints. It is conducted at hourly timescale, meaning that cost and electricity demand are provided in hourly segments. Charging efficiency is dependent on the type of electric vehicle supply equipment (EVSE). Efficiency tends to increase with higher charging rates.

If a dwell time (Δt) falls below one hour, the charge (x) available for that segment will be reduced proportional to the amount of time spent parked (i.e., if a vehicle is parked for 30 minutes, the charge will be reduced to 1/2). The default minimum dwell time to consider a charging event is 0.2 hours, or 12 minutes. This value can be modified depending on the user's scenario. The minimum dwell time is set in order to avoid impractical charging events where, in the real world, a vehicle operator would not plug in their vehicle due to the shortness of the stop. If the charging rate available is high (e.g., DC Fast Charging), a shorter minimum dwell time may be warranted.

6.2.3. NREL Electrification Futures Study Demand and Flexibility Data

The National Renewable Energy Laboratory (NREL) has developed the Electrification Futures Study (EFS) to project and study future sectoral demand changes as a result of impending widespread electrification. As a part of the EFS, NREL has published multiple reports (dating back to 2017) that describe their process for projecting demand-side growth and provide analysis of their preliminary results; all of NREL's published EFS

reports can be found [here](#). Accompanying their reports, NREL has published data sets that include hourly load profiles that were developed using processes described in the EFS reports. These hourly load profiles represent state-by-state end-use electricity demand across four sectors (Transportation, Residential Buildings, Commercial Buildings, and Industry) for three electrification scenarios (Reference, Medium, and High) and three levels of technology advancements (Slow, Moderate, and Rapid). Load profiles are provided for six separate years: 2018, 2020, 2024, 2030, 2040, and 2050. The base demand data sets and further accompanying information can be found [here](#). In addition to demand growth projections, NREL has also published data sets that include hourly profiles for flexible load. These data sets indicate the amount of demand that is considered to be flexible, as determined through the EFS. The flexibility demand profiles consider two scenarios of flexibility (Base and Enhanced), in addition to the classifications for each sector, electrification scenario, technology advancement, and year. The flexible demand data sets and further accompanying information can be found [here](#).

Widespread electrification can have a large impact on future power system planning decisions and operation. While increased electricity demand can have obvious implications for generation and transmission capacity planning, new electrified demand (e.g., electric vehicles, air source heat pumps, and heat pump water heaters) offers large amounts of potential operational flexibility to grid operators. This flexibility by demand-side resources can result in demand shifting from times of peak demand to times of peak renewable generation, presenting the opportunity to defer generation and transmission capacity upgrades. To help electrification impacts be considered properly, this package has the ability to access NREL's EFS demand data sets. Currently, users can access the base demand profiles, allowing the impacts of demand growth due to vast electrification to be explored. Users can also access the EFS flexible demand profiles.

The [NREL EFS demand notebook](#) and [NREL EFS flexibility notebook](#), illustrate the functionality of the various modules developed for obtaining and cleaning the NREL's EFS demand data.

6.3. Hydro

6.3.1. Texas

ERCOT publishes actual generation by fuel type for each 15 minute settlement interval (see the [fuel mix report](#) for more details). The profile of each hydro plant in the Texas Interconnection is then simply the ratio of the total generation provided by ERCOT di-

vided by the total hydro capacity available in the Texas Interconnection of the grid model.

The [texas hydro notebook](#) generates the profile.

6.3.2. Western

Unlike Texas, we don't have access to hourly (or sub-hourly) total generation by state or even for the whole Western Interconnection. We rely on three different methods to derive the shape of the hydro profile in California, Wyoming and the rest of the Western Interconnection.

- **California:** we use the net demand profile as a template. This is supported by data from California ISO (see [CAISO outlook](#)) showing that the hydro generation profile closely follows the net demand profile.
- **Wyoming:** we simply apply a constant shape curve to avoid peak-hour violation of maximum capacity since hydro generators have a small name plate capacities.
- **other region in the Western Interconnection:** we use the aggregated generation of the top 20 US Army Corps managed hydro dams in Northwestern US (primarily located in the state of Washington) as the shape of the hydro profile since WA has the most hydro generation in the Western Interconnection. The data is obtained via the US Army Corps of Engineers Northwestern Division DataQuery Tool 2.0 (see [USACE dataquery](#)).

The above curves are then normalized such that the monthly sum in each of the above regions is equal to the total monthly hydro generation divided by the total hydro capacity available in the grid model for the region. Note that *EIA form 923* provides the historical monthly total hydro generation by state.

The [western hydro notebook](#) generates the profile.

6.3.3. Eastern

Profile generation for the Eastern Interconnection is slightly more complex than for the Western Interconnection. First, we handle pumped storage hydro (HPS) and conventional hydro (HYC) separately. Then, in addition to using the net demand profile to derive the profile of conventional hydro plants in some state as we did for California, we also use historical hourly total hydro generation time series in some regions.

- **Pumped Storage Hydro:** We identified hydro plants in our grid model that are closely located to known HPS site in the Eastern Interconnection and created a tem-

plate to describe the hourly energy generation. The plant level profile is generated considering the local time and daylight-saving schedule of the corresponding bus location.

- **Conventional hydro:** profiles provided by [ISONNE](#), [NYISO](#), [PJM](#) and [SPP](#) are used for plants located within the area they cover. For states that are not at all covered or partially covered by the 4 ISOs the net demand demand is used as a template to derive the hydro profile using the same method that has been developed for California, i.e., the monthly net demand is normalized such that its sum is equal to the historical monthly total hydro generation (reported in [EIA form 923](#)) divided by the available total hydro capacity in the grid model. Note that for partially covered states, the historical monthly total hydro generation in the state is split proportionally to the available total hydro capacity in the grid model for the state and only the portion outside the ISOs is used during the normalization.

The [eastern hydro notebook](#) generates the profile.

6.4. Renewables

6.4.1. Solar

6.4.1.1. The National Solar Radiation Database

The [National Solar Radiation Database](#) (NSRDB) provides 1-hour resolution solar radiation data, ranging from 1998 to 2017, for the entire U.S. and a growing list of international locations on a 4x4 square kilometer grid. The [Physical Solar Model](#) (PSM) v3 is the version of the NSRDB used.

An [API](#) can be used to fetch the data. A key is required to access and use the above databases. Get your own API key [here](#).

6.4.1.2. From Solar Irradiance to Power Output

6.4.1.2.1. Naive

Power output is estimated using a simple normalization procedure. For each solar plant location in the grid model the hourly Global Horizontal Irradiance (GHI) is divided by the maximum GHI over the period considered. This procedure is referred to as naive since other factors can possibly affect the conversion from solar radiation at ground to power such as the temperature at the site as well as many system configuration includ-

ing tracking technology.

[6.4.1.2.2. System Adviser Model](#)

The [System Adviser Model](#) (SAM) developed by NREL is used to estimate the power output of a solar plant. Irradiance data along with other meteorological parameters must first be retrieved from NSRDB for each plant site. This information is then fed to the SAM Simulation Core (SCC) and the power output is retrieved. The [PySAM](#) Python package provides a wrapper around the SAM library. The [PVWatts v7](#) model is used for all the solar plants in the grid. The system size (in DC units) and the array type (fixed open rack, backtracked, 1-axis and 2-axis) is set for each solar plant whereas a unique value of 1.25 is used for the DC to AC ratio (see [article](#) from EIA on inverter loading ratios). Otherwise, all other input parameters of the PVWatts model are set to their default values. [EIA form 860](#) reports the array type used by each solar PV plant. For each solar plant in our network, the array type is a combination of the three technology and calculated via the capacity weighted average of the array type of all the plants in the EIA form that are located in the same state. If no solar plants are reported in the form for a particular state, we then consider plants belonging to the same interconnect.

[6.4.2. Wind](#)

[6.4.2.1. Rapid Refresh](#)

[RAP](#) (Rapid Refresh) is the continental-scale NOAA hourly-updated assimilation/modeling system operational at the National Centers for Environmental Prediction (NCEP). RAP covers North America and is comprised primarily of a numerical weather model and an analysis system to initialize that model. RAP provides for every hour ranging from May 2012 to date, the U and V components of the wind speed at 80 meter above ground on a 13x13 square kilometer resolution grid every hour. Data can be retrieved using the [NetCDF Subset Service](#).

[6.4.2.2. High-Resolution Rapid Refresh](#)

The [HRRR](#) (High-Resolution Rapid Refresh) is a NOAA real-time 3-km resolution, hourly updated, cloud-resolving, convection-allowing atmospheric model, initialized by 3km grids with 3km radar assimilation. Radar data is assimilated in the HRRR every 15 min over a 1-h period adding further detail to that provided by the hourly data assimilation from the 13km radar-enhanced Rapid Refresh. Data can be retrieved from a publicly available AWS S3 [Bucket](#).

6.4.2.3. From Wind Speed to Power Output

Once the U and V components of the wind are converted to a non-directional wind speed magnitude, this speed is converted to power using wind turbine power curves. Since real wind farms are not currently mapped to a grid network farms, a capacity-weighted average wind turbine power curve is created for each state based on the turbine types reported in [EIA Form 860](#). The wind turbine curve for each real wind farm is looked up from a database of curves (or the *IEC class 2* power curve provided by NREL in the [WIND documentation](#) is used for turbines without curves in the database), and scaled from the real hub heights to 80m hub heights using an alpha of 0.15. These height-scaled, turbine-specific curves are averaged to obtain a state curve translating wind speed to normalized power. States without wind farms in [EIA Form 860](#) are represented by the *IEC class 2* power curve.

Each turbine curve represents the instantaneous power from a single turbine for a given wind speed. To account for spatio-temporal variations in wind speed (i.e. an hourly average wind speed that varies through the hour, and a point-specific wind speed that varies throughout the wind farm), a distribution is used: a normal distribution with standard deviation of 40% of the average wind speed. This distribution tends to boost the power produced at lower wind speeds (since the power curve in this region is convex) and lower the power produced at higher wind speeds (since the power curve in this region is concave as the turbine tops out, and shuts down at higher wind speeds). This tracks with the wind-farm level data shown in NREL's validation report.

6.4.3. Resources

6.4.4. Command Line Interface

Wind and solar data can be downloaded via our download manager python script.

When in the terminal at the project root directory, you can run:

```
python -m prereise.cli.download.download_manager -h
usage: download_manager.py [-h] {wind_data_rap,solar_data_ga,solar_data_nsrdb}

positional arguments:
  {wind_data_rap,solar_data_ga,solar_data_nsrdb}
    wind_data_rap      Download wind data from National Centers for Environmental Prediction
    solar_data_ga      Download solar data from the Gridded Atmospheric Data
    solar_data_nsrdb   Download solar data from the National Solar Radiation Database

optional arguments:
  -h, --help            show this help message and exit
```

`-h, --help` show this `help` message and `exit`

Currently supported data sources to download from are:

- Rapid Refresh from National Centers for Environmental Prediction:

```
python -m prereise.cli.download.download_manager wind_data_rap \  
--region REGION \  
--start_date START_DATE \  
--end_date END_DATE \  
--file_path FILEPATH
```

- Gridded Atmospheric Wind Integration National Dataset Toolkit:

```
python -m prereise.cli.download.download_manager solar_data_ga \  
--region REGION \  
--start_date START_DATE \  
--end_date END_DATE \  
--file_path FILEPATH \  
--key API_KEY
```

- The National Solar Radiation Database:

```
python -m prereise.cli.download.download_manager solar_data_nsrdb \  
--region REGION \  
--method METHOD \  
--year YEAR \  
--file_path FILEPATH \  
--email EMAIL \  
--key API_KEY
```

As a concrete example, if you would like to download the wind data from Rapid Refresh from National Centers for Environmental Prediction for the Texas and Western interconnections between the dates of June 5th, 2020 and January 2nd, 2021 into `data.pkl`, you can run:

```
python -m prereise.cli.download.download_manager wind_data_rap \  
--region Texas \  
--region Western \  
--start_date 2020-05-06 \  
--end_date 2021-01-02 \  
--file_path ./data.pkl
```

Note that missing data, if existing, will be imputed using a naive Gaussian algorithm.

This can be avoided using the `--no_impute` flag.

6.4.5. Notebooks

The [RAP notebook](#) fetches the data, imputes missing data and generates a profile.

The [NSRDB SAM notebook](#) generates a solar profile by feeding the NSRDB data to SAM while the [NSRDB naive notebook](#) uses the naive method.

The [GA WIND naive notebook](#) generates solar profiles by applying the naive method to the Gridded Atmospheric Wind Integration National Dataset.

6.4.6. Bibliography

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