Recorded at time: 1733926727.683682 **ECEF** Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: 30.207 Average rate: $10\overline{0}00.0$ Average rate: 30.207 Buffer length: 4.833 Buffer length: 0.0 Buffer length: 4.833 Most recent transform: 0.0 Most recent transform: 1733926727.6 Most recent transform: 1733926727.6 Oldest transform: 1733926722.766667 Oldest transform: 1733926722.766667 Oldest transform: 0.0 FP_POI FP_ENU0 FP_ENU Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 FP_VRTK map Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 odom Broadcaster: default authority Broadcaster: default authority Average rate: $49\overline{9}.799$ Average rate: 4.742 Buffer length: 4.85 Buffer length: 4.686 Most recent transform: 1733926727.438547 Most recent transform: 1733926727.621508 Oldest transform: 1733926722.58857 Oldest transform: 1733926722.935626 lidar link base link Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 $chass is_link$ os_sensor Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 os_imu os lidar imu link

view frames Result